

μCMM

Version c



Technical Specifications

Document Version 2.5

Initiative **Fair
Data
Sheet**



The following specifications conform to the guidelines of the *Initiative Fair Datasheet*. Specifications in blue mark Alicona specific values.

Initiative Fair Datasheet

The "Fair Datasheet" considers itself a quality label to encourage manufacturers of measurement instruments to provide practice-oriented and comparable specifications. The initiative is supported by various manufacturers of measurement instruments, users such as Audi, Bosch and Daimler as well as by the Kaiserslautern University of Technology, with PTB, ZVEI and VDI considerably contributing to its operation.

Technical Specifications

GENERAL SPECIFICATIONS

Measurement principle	non-contact, optical, three-dimensional technologies: Focus-Variation with Smart Flash 2., Vertical Focus Probing and Real3D
Number of measurement points	single measurement: X: 1720, Y: 1720, X x Y: 2.95 million multi measurement: up to 500 million
Positioning volume (X x Y x Z)	310mm x 310mm x 310mm = 29,791,000mm ³
Compressed air (*)	maintenance-free with compressed air according to specification, 7 bar consumption: 80 NI/min (continuous)
Travel speed of axes	up to 100mm/s
Coaxial illumination	LED coaxial illumination (color), high-power, electronically controllable
3D data	monochrome; optional color data available
Objective changer	automatic pneumatic four-place objective changer rack
System monitoring	9 temperature sensors (accuracy: ± 0.1 K), internal current and voltage monitoring, incl. long-term logging, retrievable
ControlServerSF	6 Core, 32 GB DDR4, SSD 500 GB, Windows 10 IoT Enterprise 64bit, 2x 27" Full HD monitor
IP code	IP20
Noise emission	≤ 70 dB(A) during normal operation

DIMENSIONS AND ENVIRONMENTAL CONDITIONS

Dimensions (W x D x H)	measurement instrument: 960 x 1109 x 1958 mm (up to 2288mm); ControlServerSF: 177 x 483 x 480 mm		
Mass	measurement instrument: 1250 kg (incl. steel stand); ControlServerSF: <20 kg		
Temperature requirements	setpoint temperature range:	20 - 25 °C	
	extended setpoint temperature range (on request):	19 - 29 °C	
	ControlServerSF (possible):	0 - 30 °C	
Ambient temperature range A (high-precision measurement, VDI 2627 class 2)	permissible limit deviation of setpoint temperature:	+/- 0.8 K	
	temperature change rate:	0.8 K/d	
		0.4 K/h	
	permissible linear temperature difference:	0.3 K/m	
Ambient temperature range B (VDI 2627 class 3)	permissible limit deviation of setpoint temperature:	+/- 2 K	
	temperature change rate:	2 K/d	
		1 K/h	
	permissible linear temperature difference:	0.5 K/m	
Ambient temperature range C (reduced accuracy, VDI 2627 class 4) (larger range possible on request)	permissible limit deviation of setpoint temperature:	+/- 3 K	
	temperature change rate:	3 K/d	
		2 K/h	
	permissible linear temperature difference:	1 K/m	
Permissible relative humidity	recommended: 45 % (+/- 5 %); possible: 45 % (+/- 15 %)		
Vibrations	Recommended: < 50µg (RMS values of spectrum between 3 and 100 Hz)		
Supply voltage, current, electric power	1000 W; 100 – 240 VAC; 50 - 60 Hz		

(*) ISO 8573
 solid particles: max. number of particles per m³ < 10,000; < 5 µm class 4
 water: max. pressure dew point + 3 °C class 4
 oil: max. total oil content 5 mg/m³ class 4

MEASUREMENT OBJECT

Surface texture	any surface, including polished metals
Max. mass	30 kg, more on request
Max. dimensions	width: 680 mm height: 375 mm
Sample preparation	none

OBJECTIVE SPECIFIC FEATURES

Objective		3000 WD8	1900 WD30	1500 WD130	1500 WD23*	1500 WD70	800 WD17	800 WD37	400 WD19	150 WD11
Numerical aperture		0.075	0.12	0.14	0.15	0.14	0.3	0.2	0.4	0.6
Working distance	mm	8.8	30	130	23.5	69.4	17.5	37	19	11
Lateral measurement range (X, Y)	mm	5.26	3.23	2.63	2.63	2.63	1.32	1.32	0.66	0.26
(X x Y)	mm ²	27.64	10.43	6.91	6.91	6.91	1.71	1.71	0.43	0.06
Measurement point distance	µm	3.06	1.88	1.53	1.53	1.53	0.76	0.76	0.38	0.15
Calculated lateral optical limiting resolution	µm	4.28	2.68	2.28	2.14	2.14	1.07	1.6	0.80	0.53
Finest lateral topographic resolution	µm	6.2	3.8	3.1	3.1	3.3	1.5	1.6	0.8	0.6
Measurement noise (**)	nm	500	30	180	80	100	4	25	2	1
Vertical resolution (***)	nm	1400	85	510	230	500	30	71	20	10
Vertical measurement range	mm	8	29	125	22.5	65	16.5	36	18	10
Vertical scanning speed	µm/s	3000	3000	3000	3000	3000	1000-3000	1000-3000	500-3000	200-2000
Measurement speed		≤ 1.7 million measurement points/sec.								
Accessibility (angle)	°	47	65	77	63	76	63	70	57	46

(*) Product discontinued, availability not guaranteed.
 (**) Measurement noise N_M ; Evaluation conforming to ISO 25178-700: 2019 (under development) and Fair Datasheet V1.2
 (***) Vertical Resolution: Defined in 'Optical Measurement of Surface Topography' (ISBN 978-3-642-12012-1) and the Fair Datasheet V1.2 as $\sqrt{8}$ (square root of 8) x measurement noise. However, the vertical resolution values of Bruker Alicona are much more conservative.

RESOLUTION AND APPLICATION SPECIFICATIONS

Objective		3000 WD8	1900 WD30	1500 WD130	1500 WD23*	1500 WD70	800 WD17	800 WD37	400 WD19	150 WD11
Min. measurable height	µm	1.4	0.1	0.51	0.1	0.5	0.03	0.07	0.02	0.01
Max. measurable height	mm	8	29	125	22.5	65	16.5	36	18	10
Min. measurable roughness (Ra)	µm	n.a.	n.a.	n.a.	1.2	n.a.	0.1	0.6	0.06	0.03
Min. measurable roughness (Sa)	µm	n.a.	n.a.	n.a.	0.6	n.a.	0.05	0.3	0.03	0.02
Min. measurable radius	µm	20	12	10	10	10	5	5	3	2
Min. measurable wedge angle	°	20								
Max. measurable slope angle, standard measurement	°	87								
Max. measurable slope angle, Vertical Focus Probing	°	>90 (depending on application)								

(*) Product discontinued, availability not guaranteed.

ACCURACY

3D Accuracy 10360-8 (*)

Ambient temperature range A (VDI 2627 class 2)	$E_{\text{Uni:Tr:ODS,MPE}} = (0.8 + L/600) \mu\text{m}$ (L in mm) (**) $E_{\text{UniZ:St:ODS,MPE}} = (0.15 + L/50) \mu\text{m}$ (L in mm) (***)
Ambient temperature range B (VDI 2627 class 3)	$E_{\text{Uni:Tr:ODS,MPE}} = (0.8 + L/200) \mu\text{m}$ (L in mm) (**)
Ambient temperature range C (VDI 2627 class 4)	$E_{\text{Uni:Tr:ODS,MPE}} = (0.8 + L/100) \mu\text{m}$ (L in mm) (**)

(*) The values given are based on ISO 10360-8 and VDI 2617.

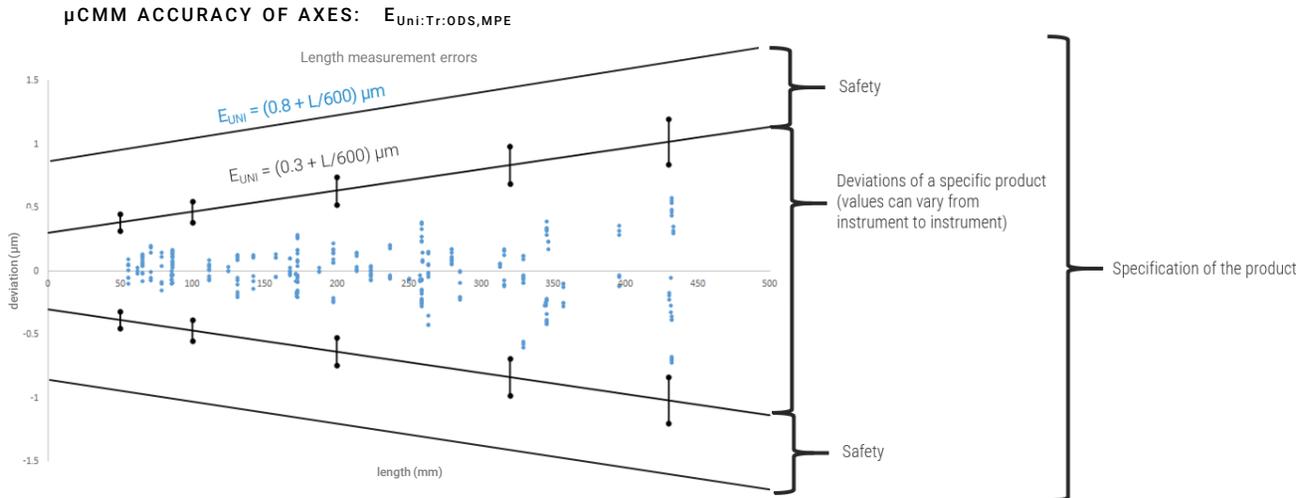
(**) Accuracy of axes based on ISO 10360-8, appendix B.4.3.4.

(***) Valid for single measurements, height step measurement.

Measurement parameters

Flatness deviation	1.3mm x 1.3mm with 800 WD17	U = 0.1 μm
Profile roughness	Ra = 0.1 μm Ra = 0.5 μm	U = 0.012 μm , $\sigma = 0.001\mu\text{m}$ U = 0.02 μm , $\sigma = 0.001\mu\text{m}$
Areal roughness	Sa = 0.1 μm Sa = 0.5 μm	U = 0.01 μm , $\sigma = 0.001\mu\text{m}$ U = 0.015 μm , $\sigma = 0.001\mu\text{m}$
Wedge angle	$\beta = 70^\circ - 110^\circ$	U = 0.075 $^\circ$, $\sigma = 0.01^\circ$
Edge radius	R = 5 μm - 20 μm R > 20 μm	U = 1.5 μm , $\sigma = 0.15\mu\text{m}$ U = 2 μm , $\sigma = 0.3\mu\text{m}$

Appendix: Accuracy



- » Each point represents a distance measurement of a specific length.
- » 5 lengths, 3 times, 7 directions, according to ISO 10360-8
- » Test uncertainty according to ISO 23165: $U(k=2) = 0.05 \mu\text{m} + 0.3 \mu\text{m}/\text{m}$ (laser interferometer)

Relation between E_{Bi} and E_{Uni}

ISO 10360 deals with the acceptance and reverification tests for coordinate measuring systems (CMS). In part 8, CMMs with optical distance sensors are discussed*, using the length measurement errors E_{Bi} and E_{Uni} for verification. In case of optical measuring instruments, the relevant parameter for real measurement application is E_{Uni} due to the measuring direction. Using method B (see ISO 10360-8, section 6.3.5.3), E_{Bi} can be calculated from the measured and the calibrated length measurement errors as well as the probing form and size errors P_{Form} and P_{Size} .

Assuming:

- $E_{Uni} = (0.3 + L/600)\mu\text{m}$
- $P_{Form.Sph.1x25j:ODS} = 0.405\mu\text{m}$
- $P_{Size.Sph.All:St:ODS} = 0.12\mu\text{m}$

Using method B, $E_{Bi:j:ODS}$ can be calculated based on the 105 measured and calibrated values $L_{Uni:meas}$ and $L_{Uni:cal}$:

- $L_{Uni:meas} - L_{Uni:cal} + P_{Size.Sph.1x25j:ODS} > 0 \rightarrow E_{Bi:j:ODS} < L_{Uni:meas} - L_{Uni:cal} + P_{Size.Sph.1x25j:ODS} + P_{Form.Sph.1x25j:ODS}$
- $L_{Uni:meas} - L_{Uni:cal} + P_{Size.Sph.1x25j:ODS} < 0 \rightarrow E_{Bi:j:ODS} > L_{Uni:meas} - L_{Uni:cal} + P_{Size.Sph.1x25j:ODS} - P_{Form.Sph.1x25j:ODS}$

Plot all errors \rightarrow results in $E_{Bi:ODS} = (0.65 + L/600)\mu\text{m}$

**Note that ISO 10360-8 has limited applicability to an optical micro-coordinate measuring machine such as the μCMM. Reasons for this are:*

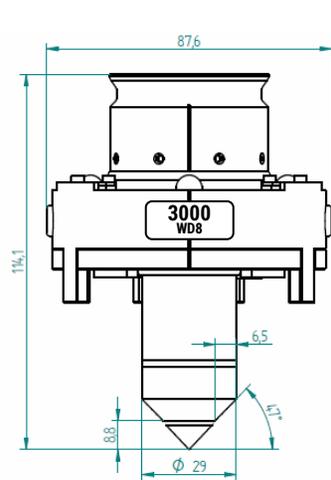
- *The standard specifies that the spheres to be measured have a diameter of 10-51mm. This is not possible with a single field measurement on a microcoordinate measuring machine like the μCMM. It requires an image field measurement, which necessitates moving the sensor head and the stitching of several single field measurements. This is not covered by ISO 10360-8. The spheres on the calibration standards used by Bruker Alicona therefore have a diameter of 1mm.*
- *A bidirectional length measurement (E_{Bi}) is stipulated in the standard for historical reasons, as it was established when using tactile measuring methods. Optical measuring instruments typically measure unidirectional, which means that a requirement for bidirectional evaluation is far from practice.*
- *The standard is designed for point measurements as known from tactile measuring devices. The extension to point clouds is only marginally provided for in ISO 10360-8. However, due to the small tolerances, optical measuring devices for microcoordinate metrology measure small dimensions using geometry elements based on point clouds. This means that a requirement for point measurements is neither viable nor suitable for application.*

Currently, the guideline VDI/VDE 2617 Sheet 12.2 is being developed according to ISO 10360-8 in the VDI/VDE Technical Committee 3.31, which deals in detail with the topic of acceptance and reverification testing for coordinate measuring machines for the optical measurement of micro-geometries.

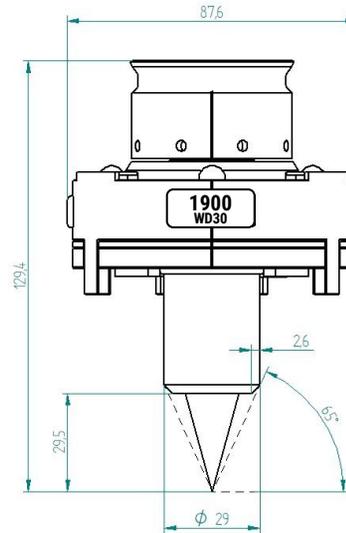
Relation between E_{Uniz} and uncertainty of profile roughness

Since the Rz value is typically 6 times as high as the Ra value, the uncertainty of the Rz value is also 6 times as high as the uncertainty of the Ra value. If the influence of the λ_c filter is considered as well, the result is E_{Uniz}

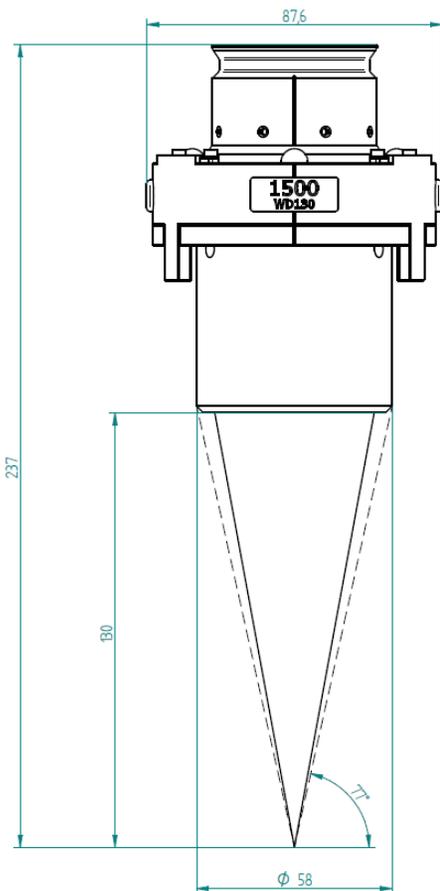
Objectives: Accessibility and Dimensions



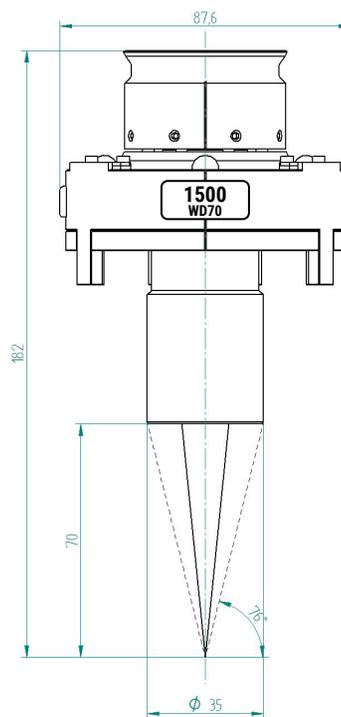
μCMMObjective3000 WD8
accessibility: 47°



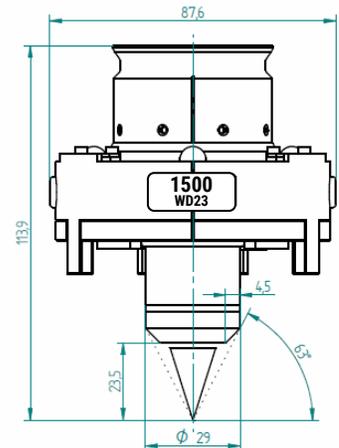
μCMMObjective1900 WD30
accessibility: 65°



μCMMObjective1500 WD130
accessibility: 77°



μCMMObjective1500 WD70
accessibility: 76°



μCMMObjective1500 WD23*
accessibility: 63°

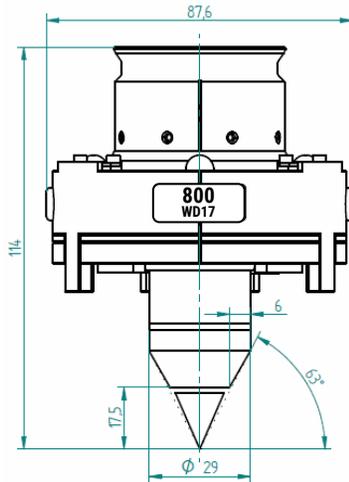
* product discontinued, availability not guaranteed.

Notice About Objective Names:

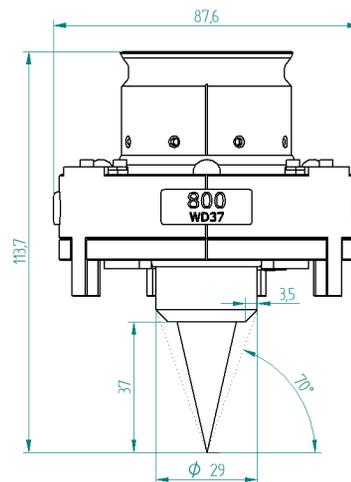
To enable a more precise differentiation, objective names have been expanded to include the working distance in their name.

Formerly	New name	Formerly	New name
3000A	3000 WD8	800A	800 WD17
1500B	1500 WD70	400A	400 WD19
1500A	1500 WD23	150A	150 WD11

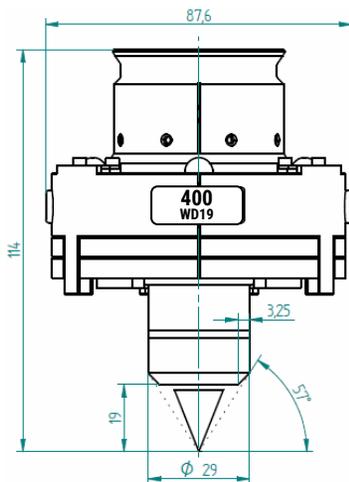
Objectives: Accessibility and Dimensions



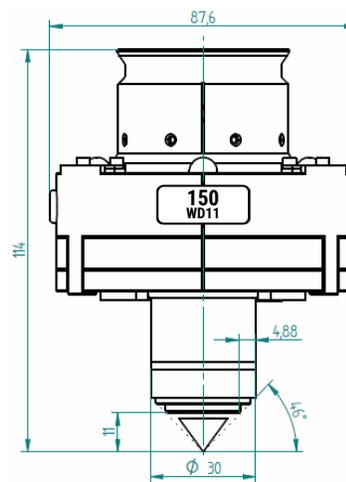
μCMMObjective800 WD17
accessibility: 63°



μCMMObjective800 WD37
accessibility: 70°

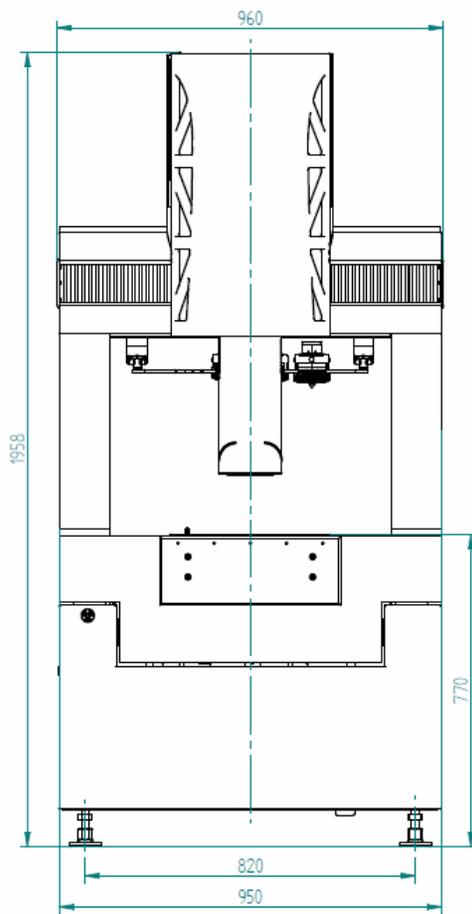


μCMMObjective400 WD19
accessibility: 57°

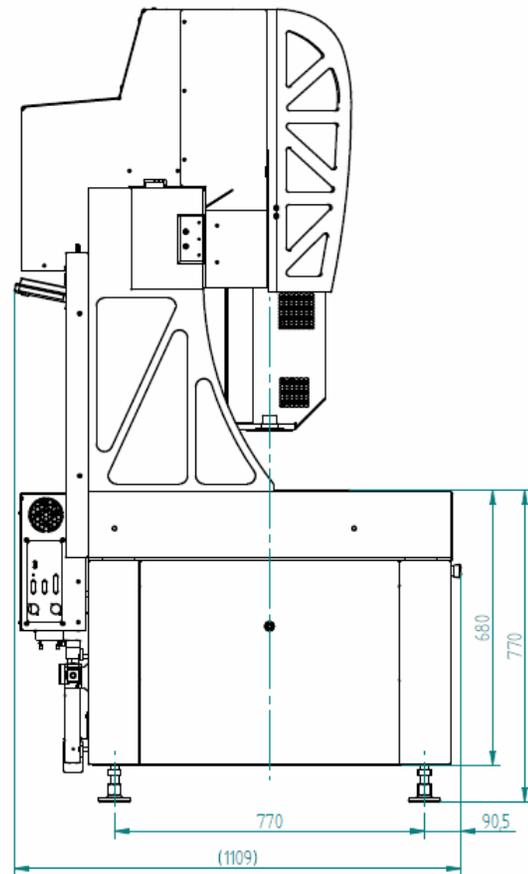


μCMMObjective150 WD11
accessibility: 46°

Technical Drawings

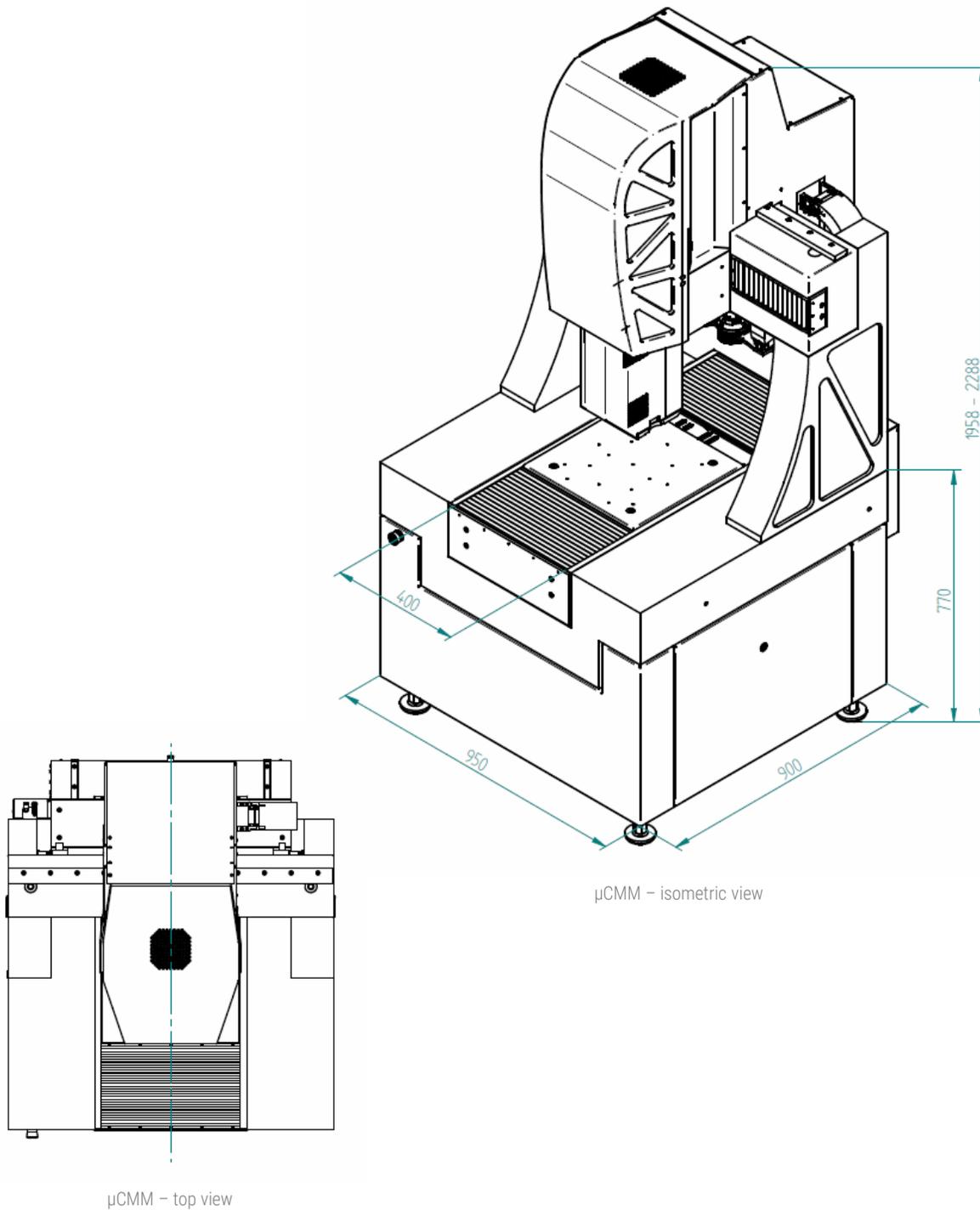


μCMM – front view
(sensor in lowest position)

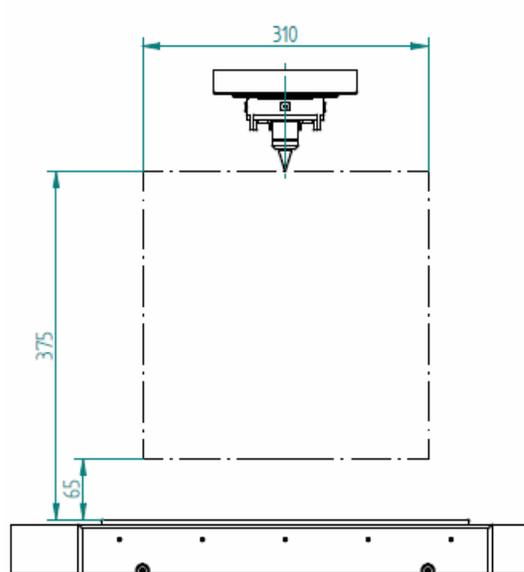


μCMM – side view

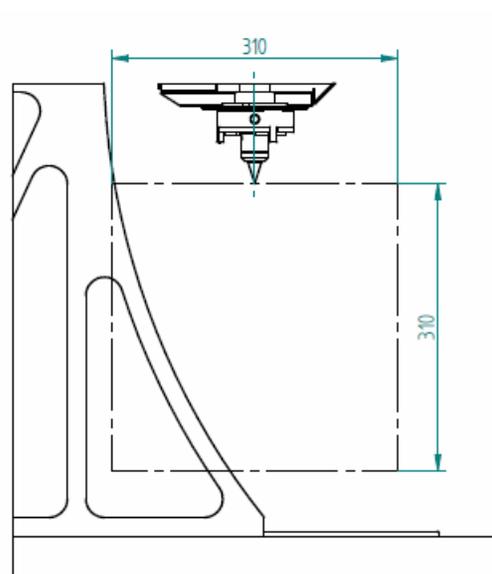
Technical Drawings



Technical Drawings

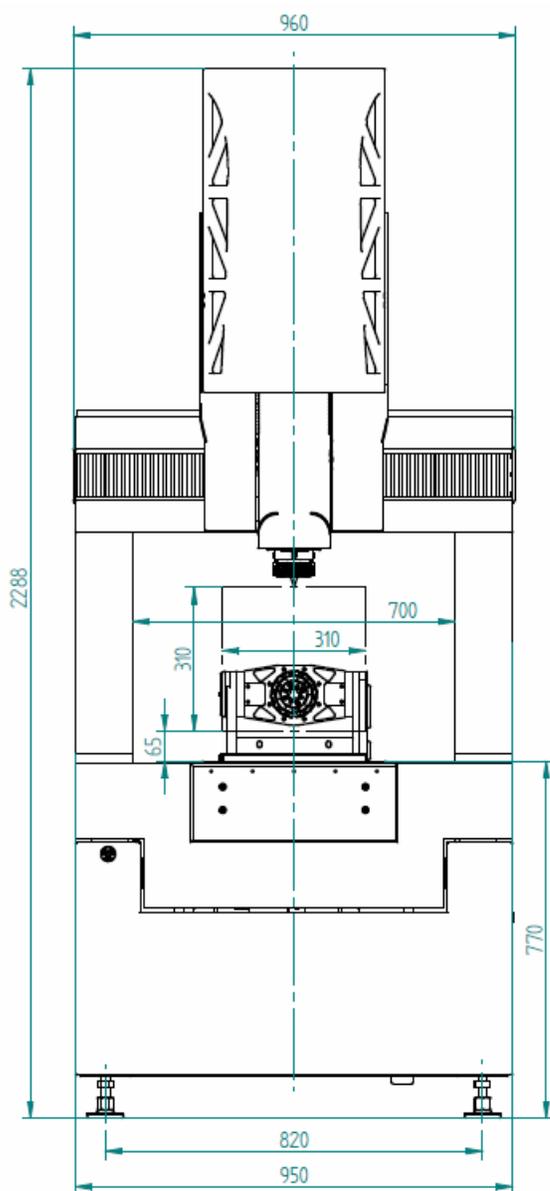


μCMM – positioning volume, front view

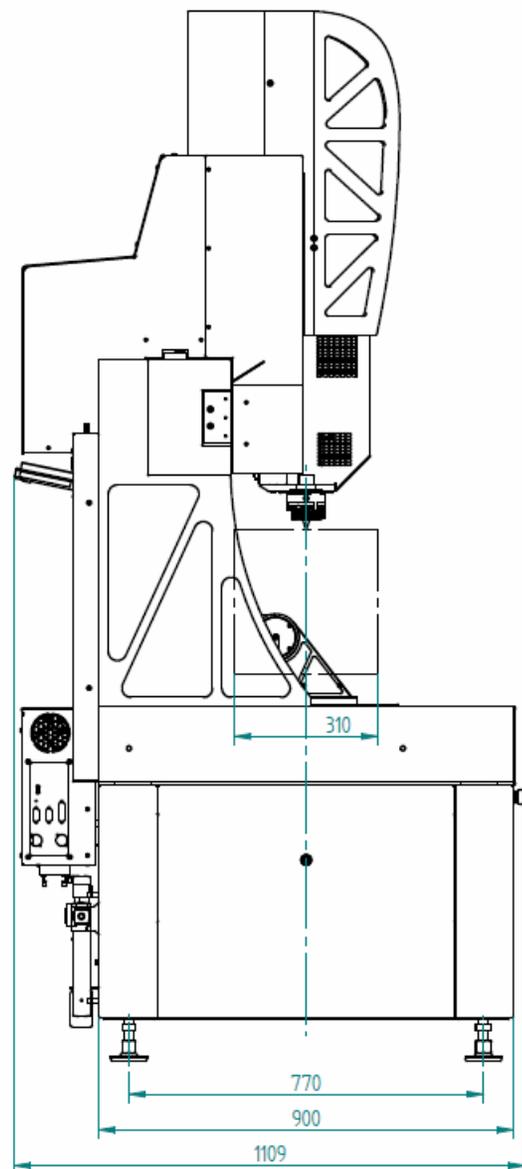


μCMM – positioning volume, side view

Technical Drawings with μ CMMReal3D

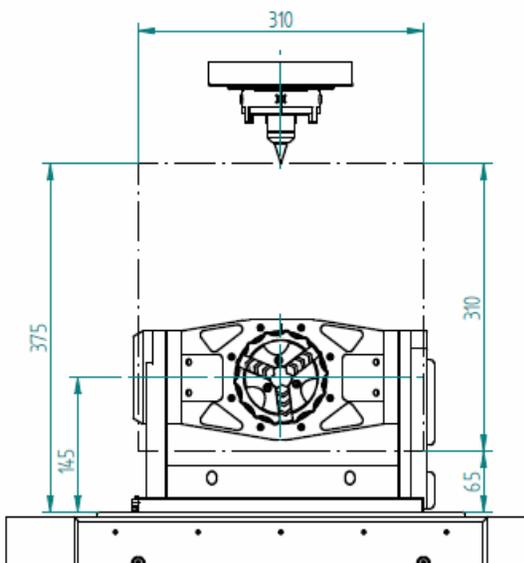


μ CMM – front view with μ CMMReal3D

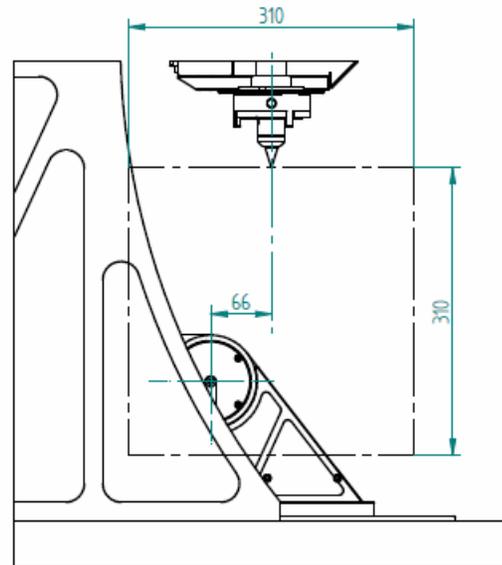


μ CMM – side view with μ CMMReal3D

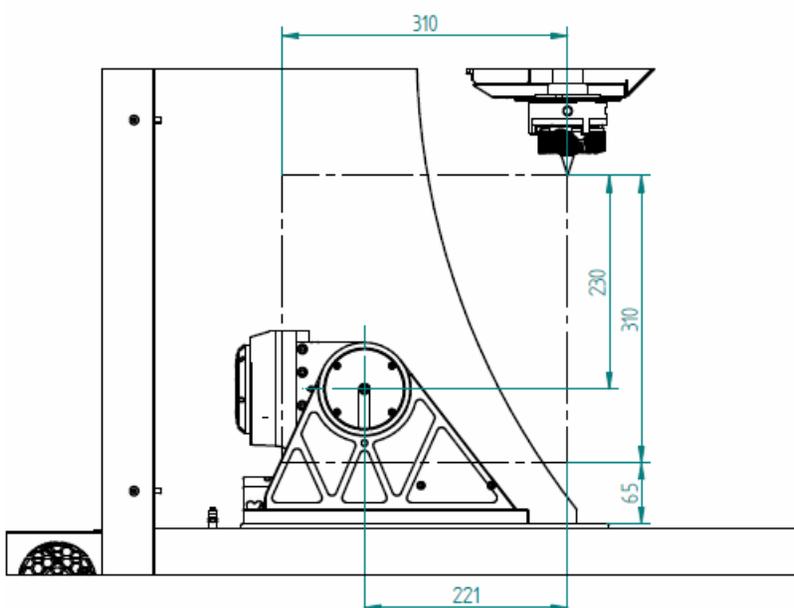
Technical Drawings with μ CMMReal3D



μ CMM – positioning volume
with μ CMMReal3D, front view

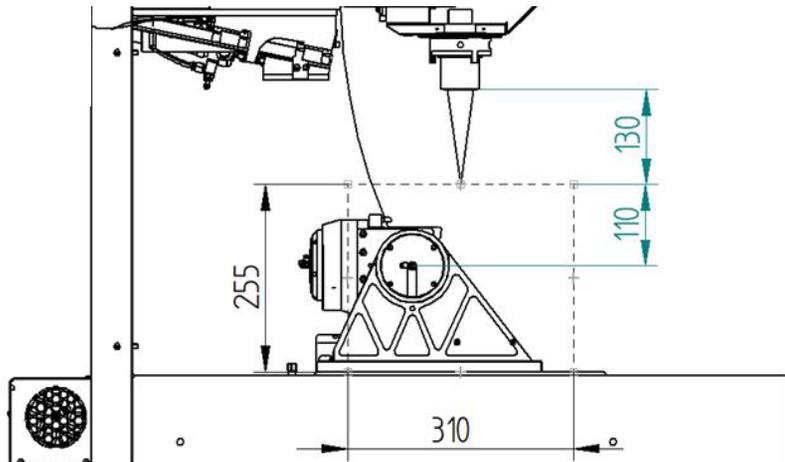


μ CMM – positioning volume
with μ CMMReal3D, side view,
Y axis in middle position



μ CMM – positioning volume with
 μ CMMReal3D,
side view,
Y axis in rearmost position

Technical Drawings with μ CMMReal3D



μ CMM – positioning volume with μ CMMReal3D
and μ CMMObjective 1500 WD130,
side view,
Y axis in middle position

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